



9th International Interdisciplinary Congress on Renewable Energies, Industrial Maintenance, Mechatronics and Informatics

Booklets



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Title: State Estimation of Discrete Event Systems Using Fuzzy Timed Petri Nets

Authors: González-Castolo, Juan Carlos, López-Mellado, Ernesto, Ramos-Cabral, Silvia and Zataráin-Durán, Omar Alí

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Park Pedregal Business. 3580,
Anillo Perif., San Jerónimo
Aculco, Álvaro Obregón,
01900 Ciudad de México, CDMX,
Phone: +52 1 55 6159 2296
Skype: ecorfan-mexico.s.c.
E-mail: contacto@ecorfan.org
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PRESENTATION CONTENT

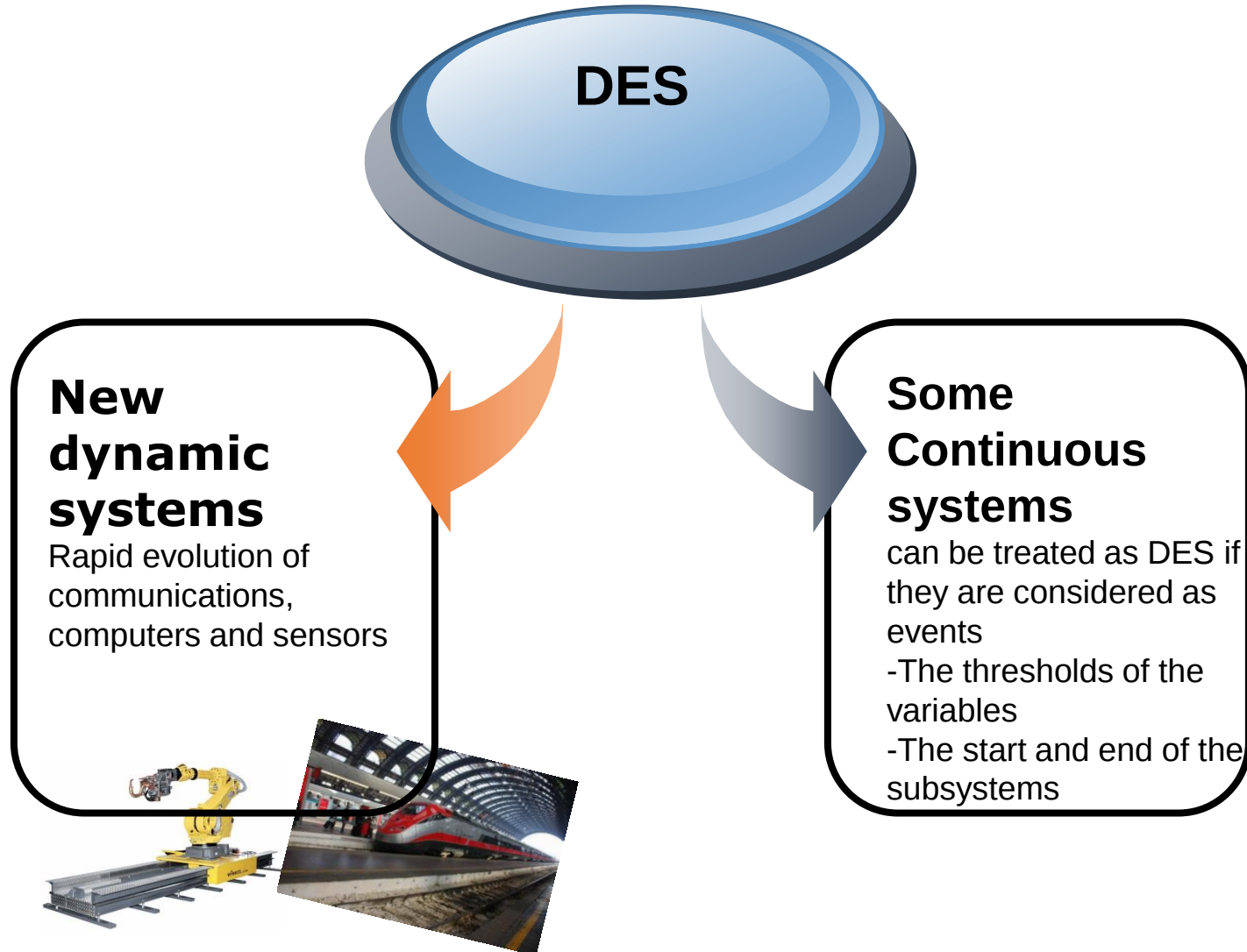
Introduction

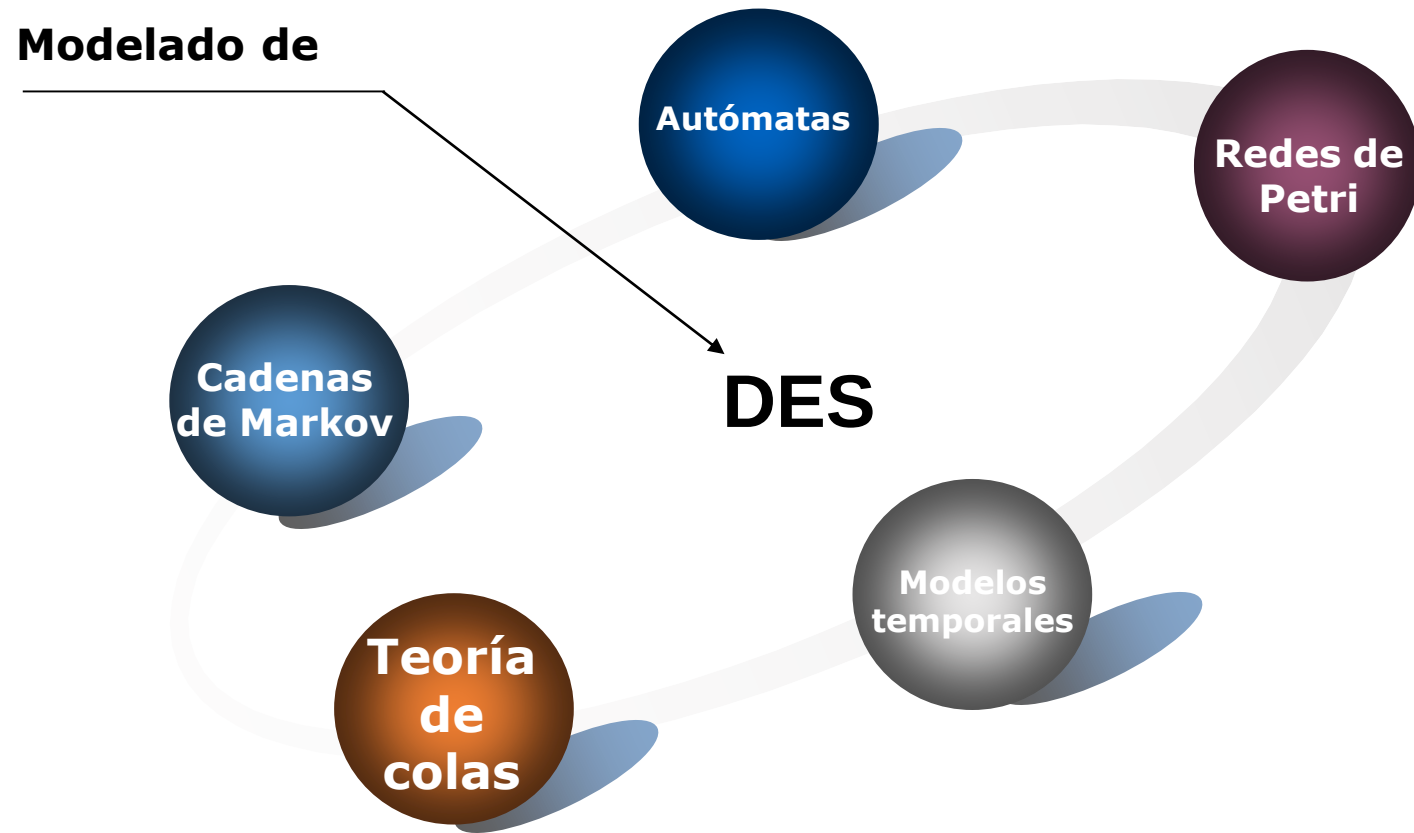
Background

Fuzzy Timed Petri Nets

Measurable places in a FTPN

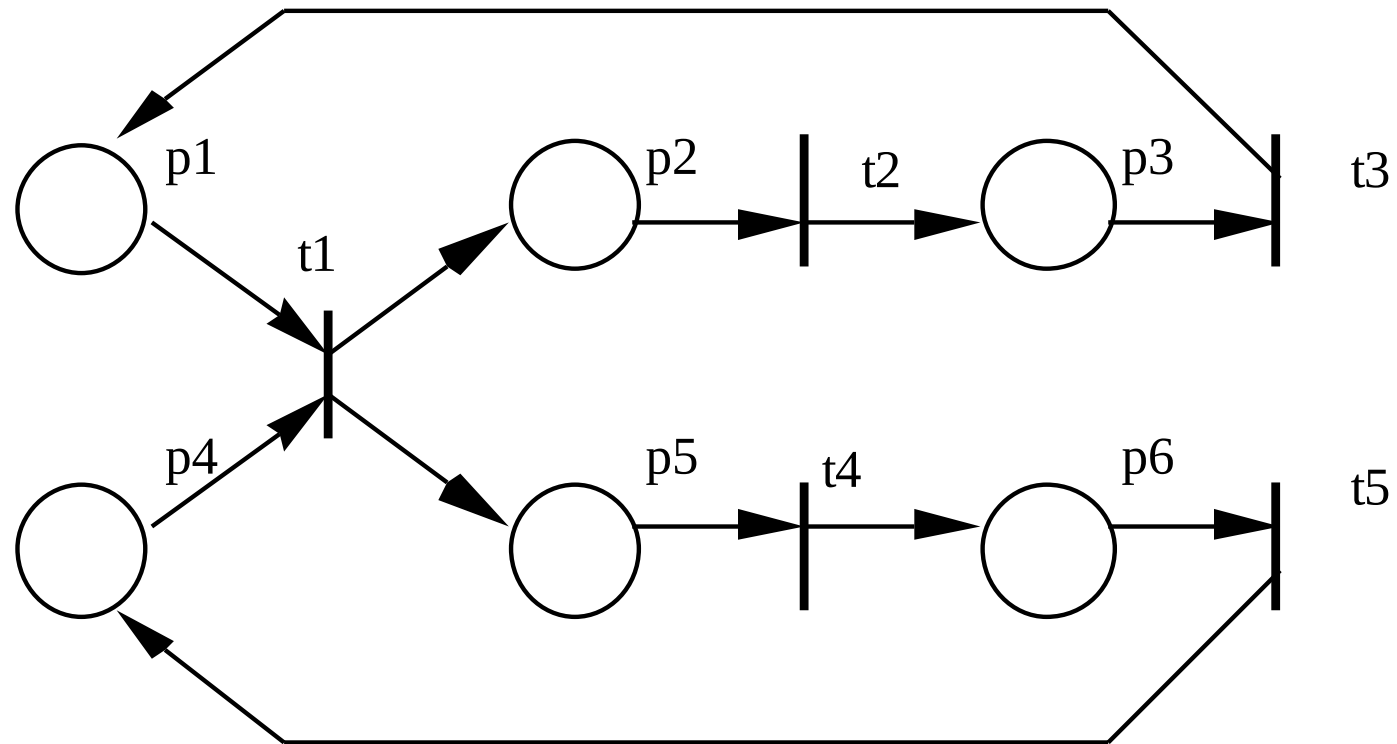
Conclusions



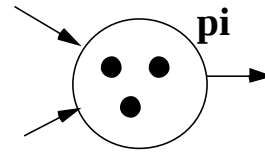


Background: Redes de Petri

Estructura de la PN $\rightarrow$ Grafo bipartita



Distribución de marcas o tokens (puntos) dentro de los lugares



Marcado inicial (M_0): Localización inicial de la marca

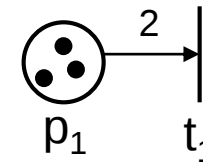
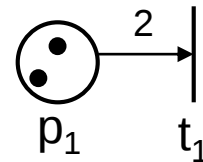
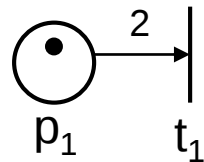
- Lugares de entrada $\bullet t_j$,
- Lugares de salida $t_j \bullet$

Background: Redes de Petri

Evolución del marcado $\rightarrow$ **regla de transición**
en dos partes

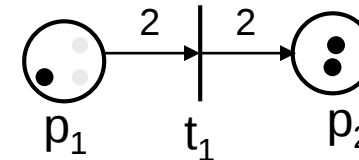
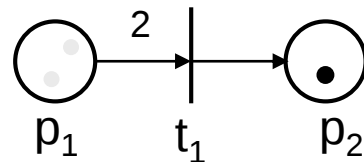
Transición habilitada:

- El lugar de entrada debe tener al menos tantas marcas como lo requiera el peso de los arcos de entrada

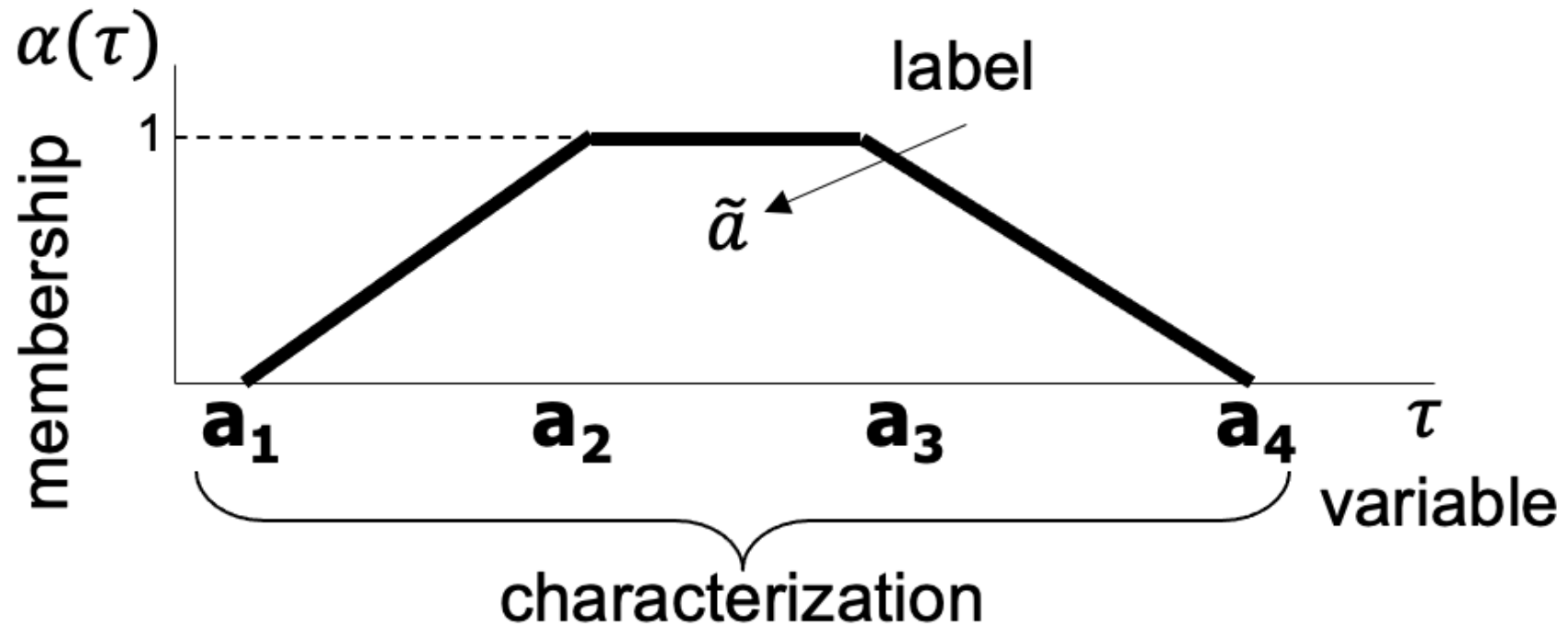


Disparo de transición:

- Remover las marcas de los lugares de entrada según lo indique el peso de los arcos de entrada
- Agregar marcas a los lugares de salida según lo indique el peso de los arcos de salida

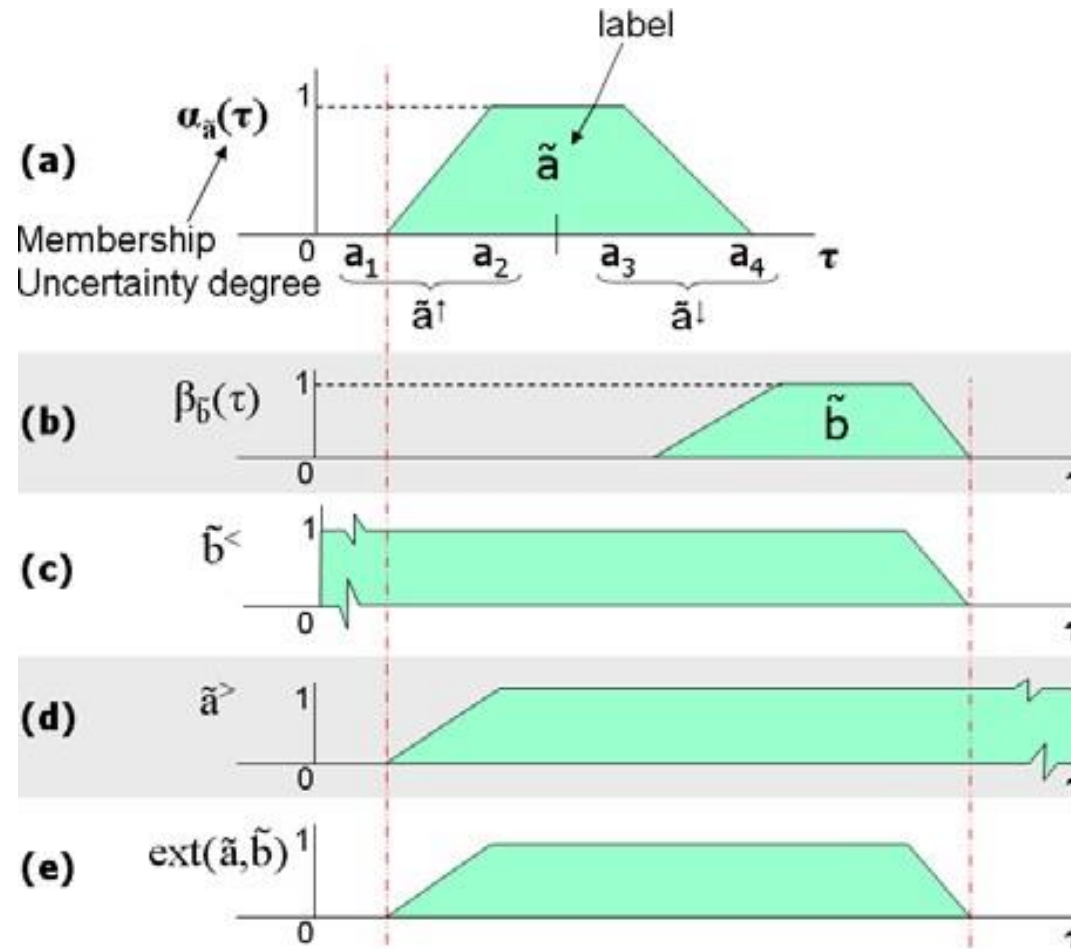


Background: Fuzzy Logic



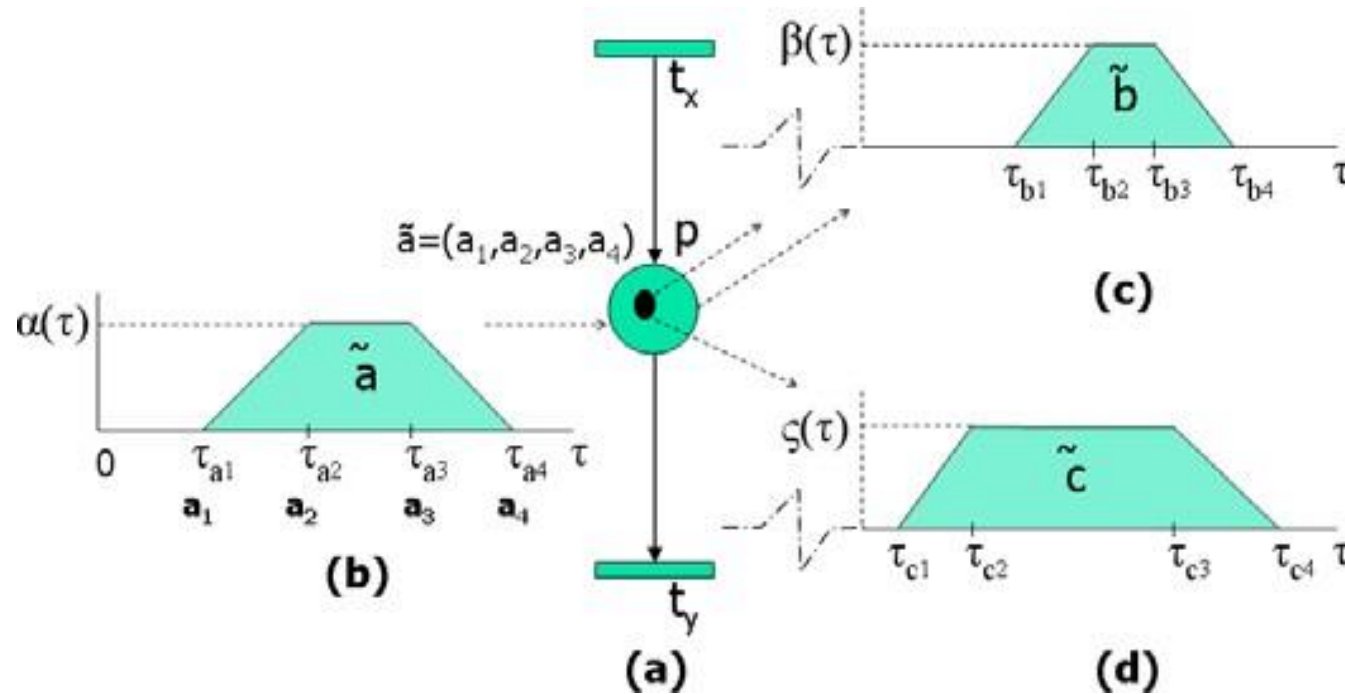
Fuzzy set

Background: Fuzzy Logic



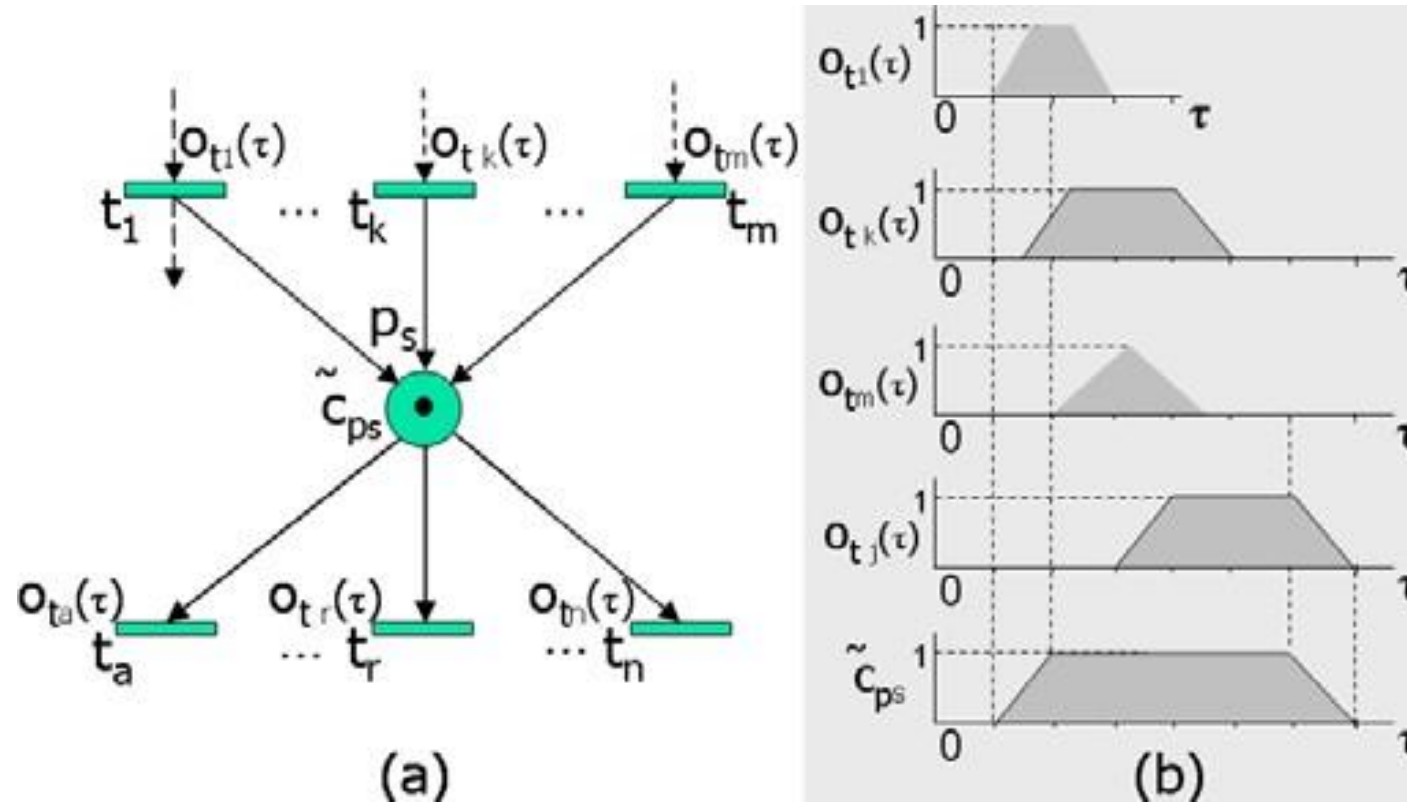
Fuzzy sets and operations

Fuzzy Timed Petri Nets



(a) Fuzzy Petri net, (b) The fuzzy set associated to places. (c) Fuzzy set to place or mark associated. (d) Fuzzy timestamp

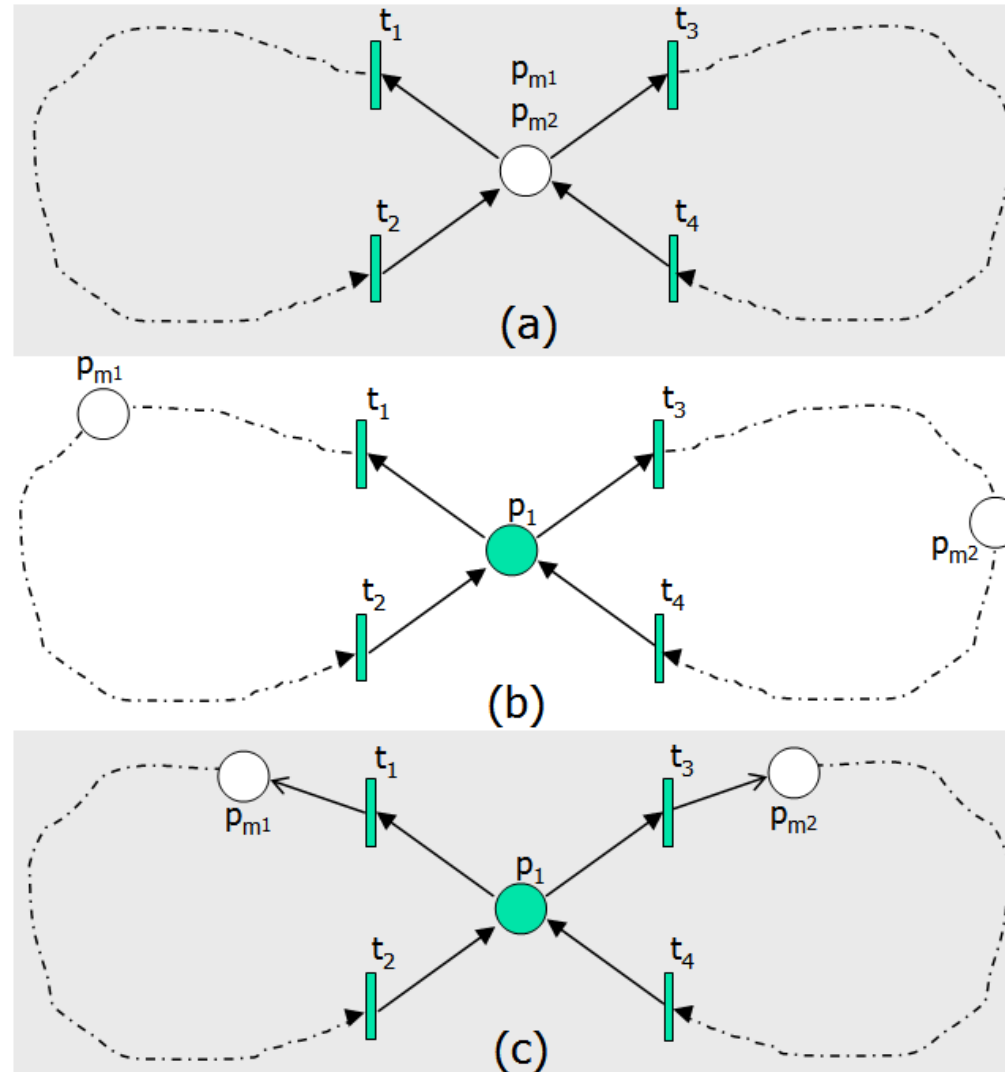
Fuzzy Timed Petri Nets



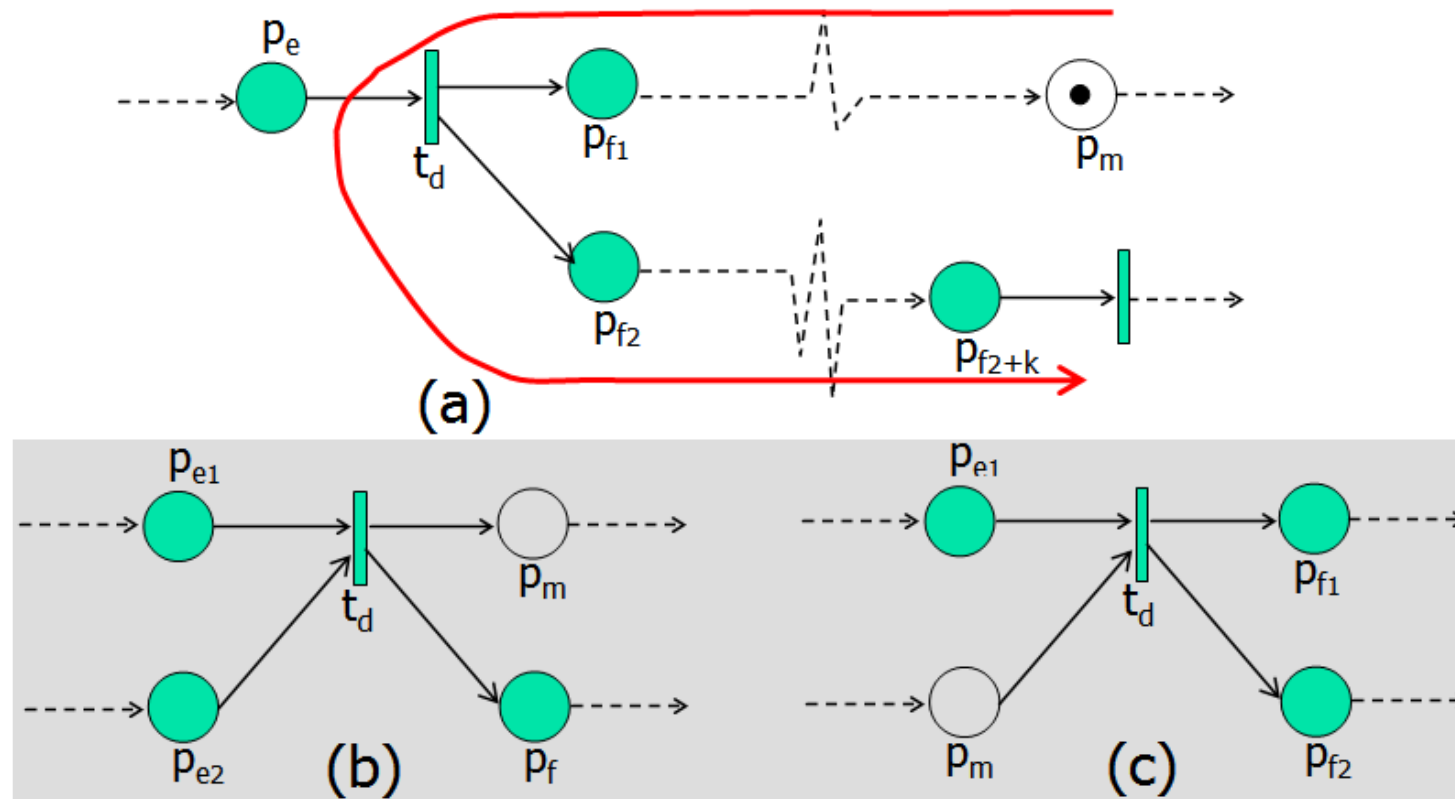
(a) Attribution and selection place. (b) Fuzzy timestamp computing

Measurables Places in a FTPN

Fuzzy marking evolution

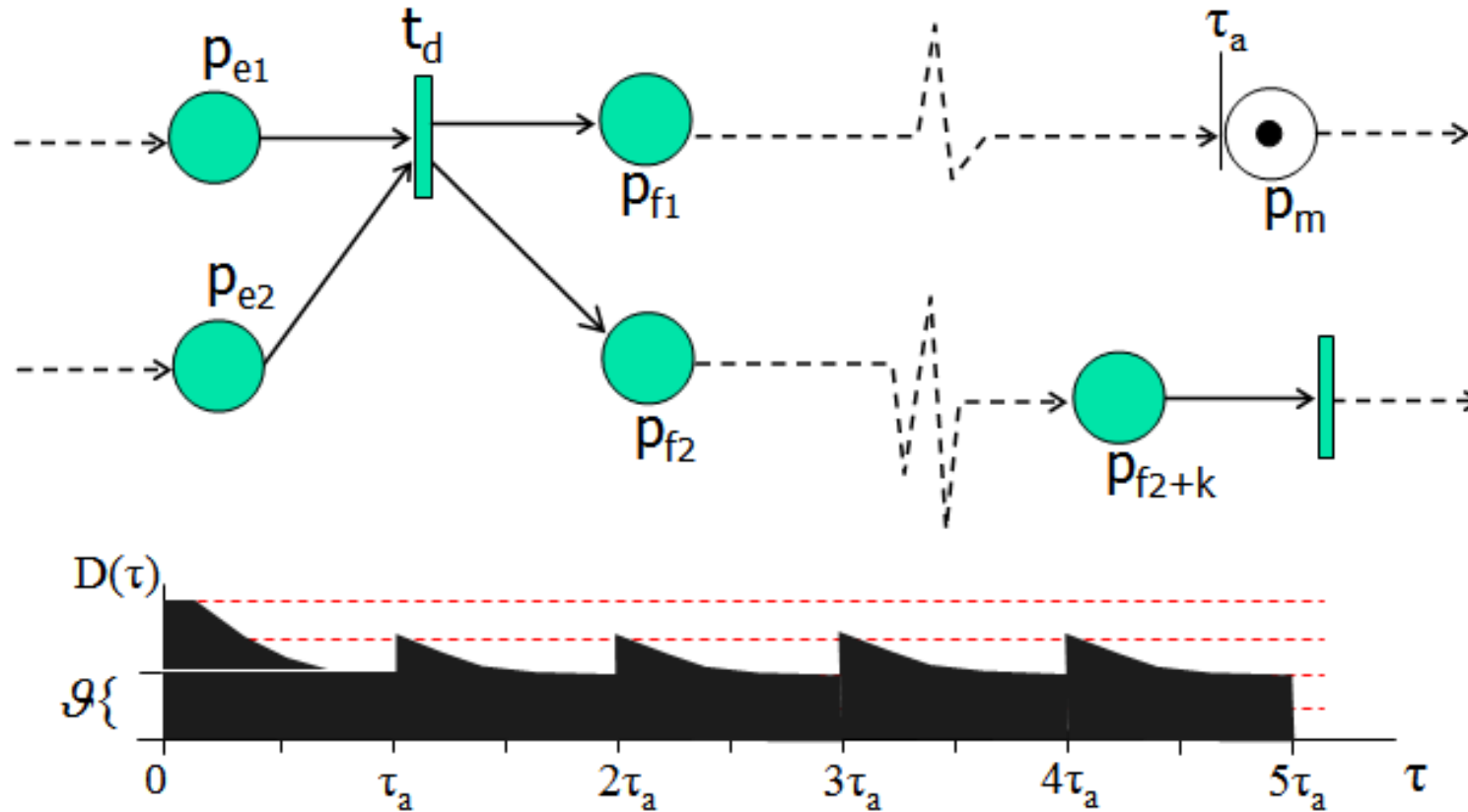


Measurables Places in a FTPN



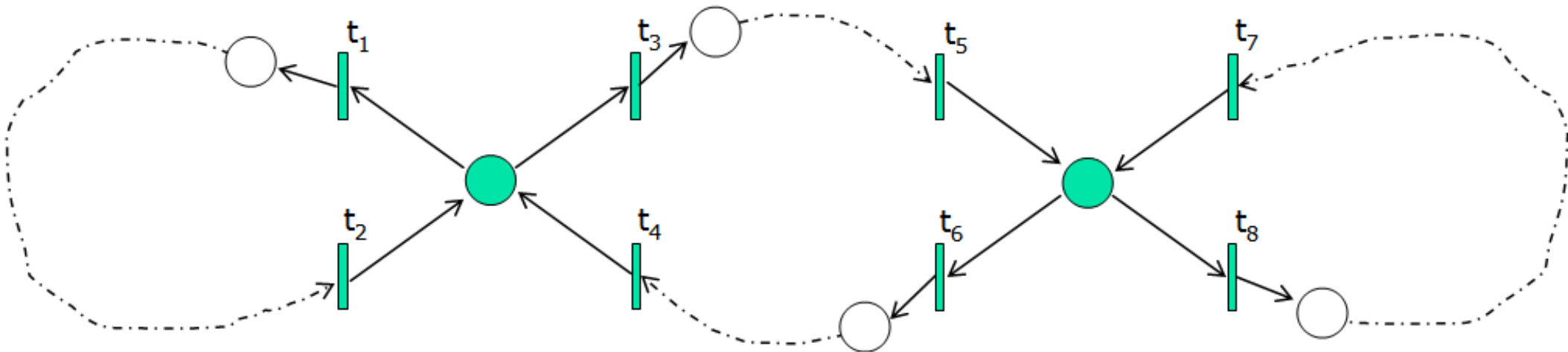
Location of places with associated sensor signals

Measurables Places in a FTPN



Quality of state estimate ϑ

Measurables Places in a FTPN



FTSM with more than one measurable place by t-component

Conclusions

This paper addressed the problem of DES state estimation for which activity durations are poorly known; fuzzy sets represent the uncertainty of the end of activities.

Current research addresses the inclusion of sensors in FTPN to reduce the uncertainty about marking the observed locations to zero and to keep the uncertainty of marking bounded for any evolution of the system.

The inclusion of sensory information in the fuzzy model, called semi-fuzzy in this case, allows to keep the uncertainty in the approximation of marking bounded.

The analysis presented shows that a reduced number of sensors is enough to give this property to the state estimation device.



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Questions?

jcgcastolo@cucea.udg.mx

silvia.ramos@academicos.udg.mx

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